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By Ian Fischer

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This well-organized book uses 3×3 coordinate-transformation matrices and 3-element vectors with dual-number elements to analyze the mechanics of mechanism, robots, and other mechanical systems.

Dual-Number Methods in Kinematics, Statics and Dynamics serves as a text for a course using dual-number methods as well as a manual for the reader to develop his or her abilities for the design of machinery or evaluation of mechanical systems. In addition to the explanatory text and derivations, the author includes numerous examples and exercises to enable the reader to gain insight and perfect skills.

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